

Vectors

Equal vectors:

$$\vec{a} = \vec{b}$$

For $\vec{a} = \vec{b}$, all components of \vec{a} must be equal to \vec{b} :

$$\vec{a} = a_x \hat{i} + a_y \hat{j} + a_z \hat{k}$$

$$\vec{b} = b_x \hat{i} + b_y \hat{j} + b_z \hat{k}$$

If $\vec{a} = \vec{b}$ then

$$\begin{cases} a_x = b_x \\ a_y = b_y \\ a_z = b_z \end{cases}$$

Example

Find x, y, z in the following vector equation.

$$x \hat{i} + (x+y) \hat{j} + (x+y+2z) \hat{k} = \hat{i} + 2 \hat{k}$$

$x = ?$ $y = ?$ $z = ?$ $1x \hat{i} + 0x \hat{j}$

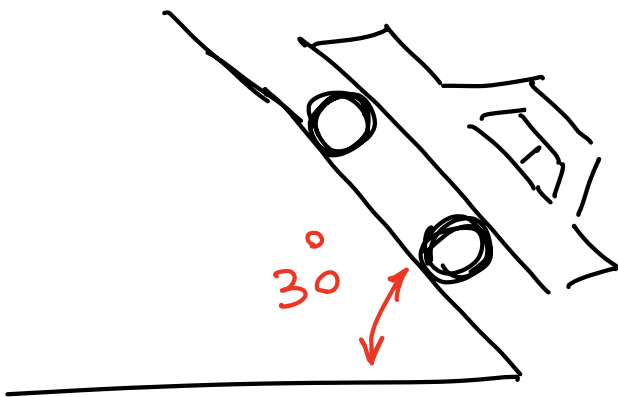
$$\left. \begin{array}{l} x = 1 \quad \textcircled{1} \\ x + y = 0 \quad \textcircled{2} \\ x + y + 2z = 2 \quad \textcircled{3} \end{array} \right\} \Rightarrow \begin{array}{l} 1 + y = 0 \\ y = -1 \\ 1 - 1 + 2z = 2 \\ z = 1 \end{array}$$

Example

The vehicle is not moving in the figure below. Find the

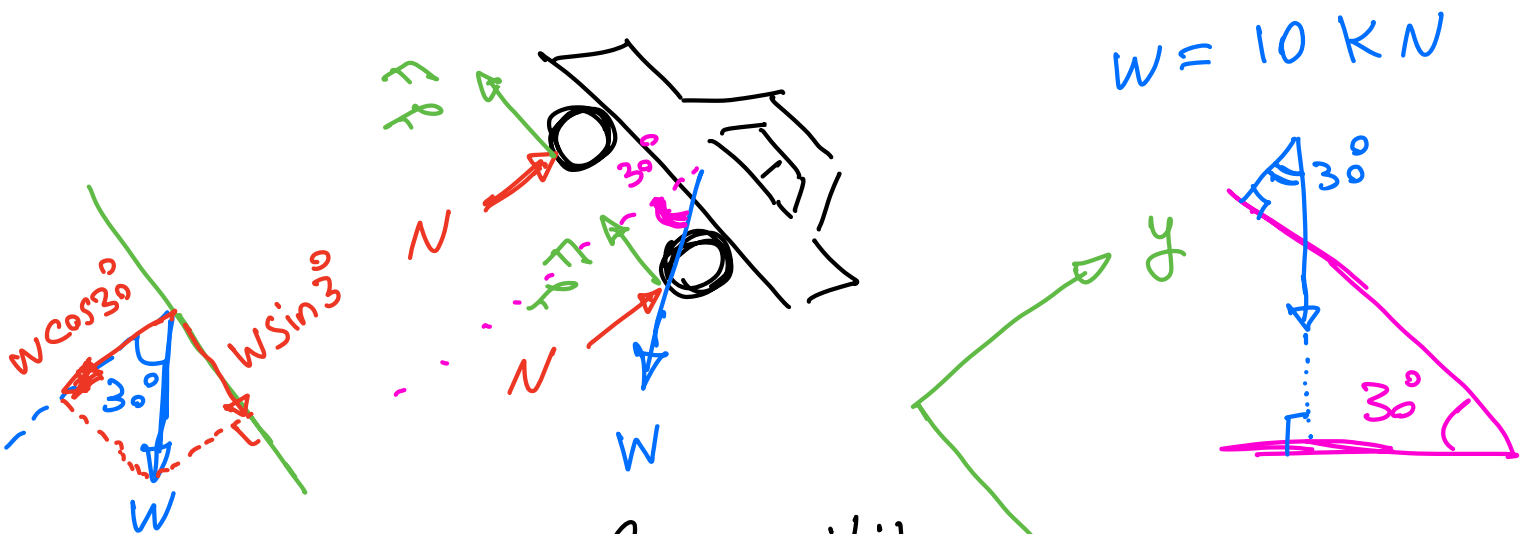
Friction force F_b .

The weight of the vehicle is $w = 10 \text{ kN}$



Always start with free-body-diagram

F. B. D.



Equations of Equilibrium

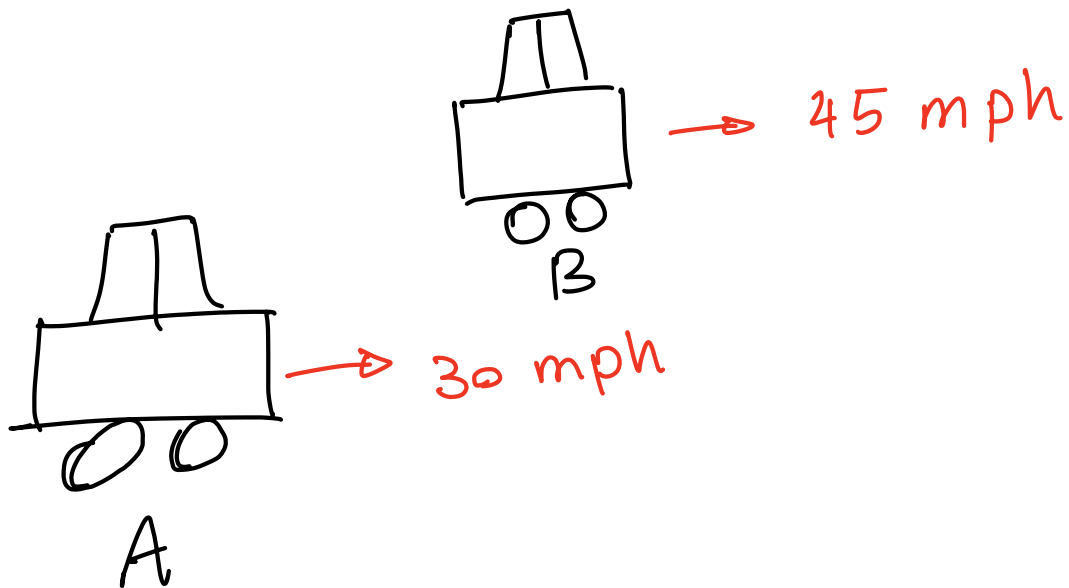
$$\begin{cases} \Sigma F_x = 0 & \Rightarrow +W \sin 30^\circ - 2F_f = 0 \\ \Sigma F_y = 0 & \Rightarrow +2N - W \cos 30^\circ = 0 \end{cases}$$

Alternatively:

Equations in vector form:

$$\Sigma \vec{F} = 0 \quad \Rightarrow \quad +W \sin 30^\circ \hat{i} - 2F_f \hat{i} + 2N \hat{j} - W \cos 30^\circ \hat{j} = 0$$

Relative velocity



The speed of B with respect to A is $V_{B/A} = 45 \text{ mph} - 30 \text{ mph} = 15 \text{ mph}$

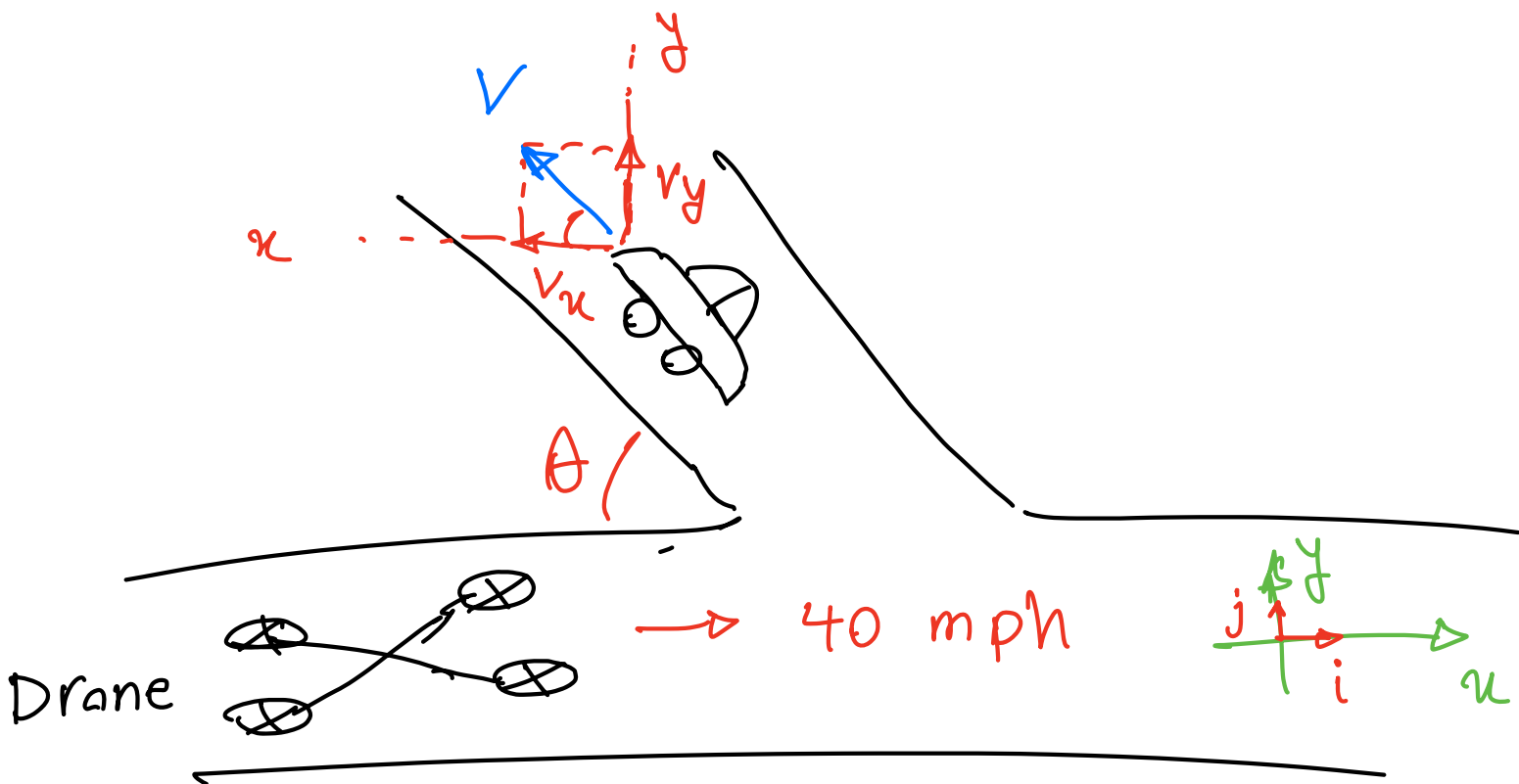
In general the velocity of B relative to A can be written as:

$$\text{Relative } \vec{V}_{B/A} = \vec{V}_B - \vec{V}_A$$

Absolute *Absolute*

Example

A drone flying at 40 mph is measuring the speed of a vehicle as shown below.



If the drone measures the speed of the vehicle as

$$\vec{V}_{\text{vehicle/Drone}} = -20 \text{ mph } \hat{i} + 5 \text{ mph } \hat{j}$$

Find the speed of the vehicle (Absolute)

$$\vec{V}_{\text{vehicle}} = -V \cos \theta \hat{i} + V \sin \theta \hat{j}$$

$$\vec{V}_{\frac{\text{vehicle}}{\text{Drone}}} = \vec{V}_{\text{vehicle}} - \vec{V}_{\text{Drone}}$$

$$\vec{V}_{\text{Drone}} = 40 \hat{i}$$

$$\vec{V}_{\frac{\text{vehicle}}{\text{Drone}}} = -V \cos \theta \hat{i} + V \sin \theta \hat{j}$$
$$-40 \hat{i} = -20 \hat{i} + 5 \hat{j}$$

$$\begin{cases} V \cos \theta + 40 = 20 & \rightarrow V \cos \theta = -20 \\ V \sin \theta = 5 \end{cases}$$

$$\Rightarrow V \approx 21$$