

## Multiplication

### Rectangular

$$z = x + iy$$

$$\bar{z} = x - iy \quad \text{conjugate}$$

$$z\bar{z} = (x + iy)(x - iy)$$

$$= x^2 - x(iy) + iy(x) - iy \cdot iy$$

$$\therefore = x^2 - i^2 y^2 = x^2 + y^2$$

$$\boxed{i = \sqrt{-1} \Rightarrow i^2 = -1}$$

## Multiplication

### Polar form

$$z_1 = r_1 e^{i\theta_1}$$

$$z_2 = r_2 e^{i\theta_2}$$

$$z_1 z_2 = r_1 r_2 e^{i\theta_1} e^{i\theta_2}$$

$$= r_1 r_2 e^{i(\theta_1 + \theta_2)}$$


---

Multiply the conjugate in polar:

$$z = r e^{i\theta}$$

$$\bar{z} = r e^{-i\theta} \quad \text{conjugate}$$

$$z \bar{z} = r e^{i\theta} r e^{-i\theta} = r^2 e^{i(\theta - \theta)} = r^2$$


---

Division

In dividing complex numbers, we  
don't want any complex number in  
the denominator (remove i from the  
denominator)

## Example

$$\frac{1}{i} = ?$$

$$\frac{1}{i} \cdot \frac{i}{i} = \frac{i}{i^2} = -i$$

$$i = x + iy$$

$\downarrow$        $\downarrow$

$$x=0 \quad y=1$$

$$10 = x + iy$$

$\downarrow$        $\nwarrow$

$$10 \quad y=0$$

## Example

$$\frac{1}{2-3i} = ?$$

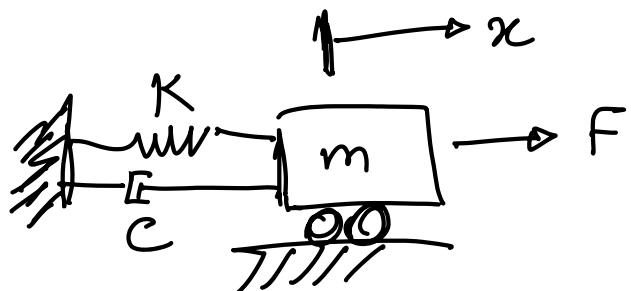
use the conjugate to remove "i" from  
the denominator:

$$\frac{1}{2-3i} \cdot \frac{2+3i}{2+3i} = \frac{2+3i}{4+9} = \frac{2+3i}{13}$$

$(2-3i)(2+3i) = 4 - 9i^2 - 6i + 6i = 4+9$

## Example

find the amplitude of oscillation in the mass-spring example below.



F is the input force

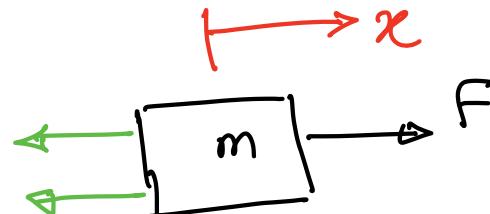
x is the displacement of the mass

K : stiffness of the spring

C : Damping constant of the damper

## Free-body-diagram (F.B.D)

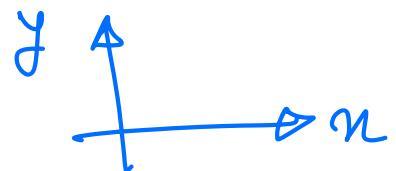
Force of the  
spring:  $Kx$



$$\dot{x} = \frac{dn}{dt}$$

Velocity

$C\dot{x}$   
Force  
of  
the damper



Equations of motion:

$$\sum \vec{F} = m \vec{a}$$

$$F - c\dot{x} - kx = m\ddot{x}$$

$$\ddot{x} = \frac{d^2 x}{dt^2} = a$$

acceleration

Let's assume that the solution for displacement is in the following form:

$$x = A e^{i\omega t}$$

$\omega$  is the angular frequency

Amplitude of oscillation

Frequency (Hz) =  $\frac{\text{cycle}}{\text{second}}$

$$\omega (\text{angular freq. } \frac{\text{rad}}{\text{s}}) = 2\pi f$$

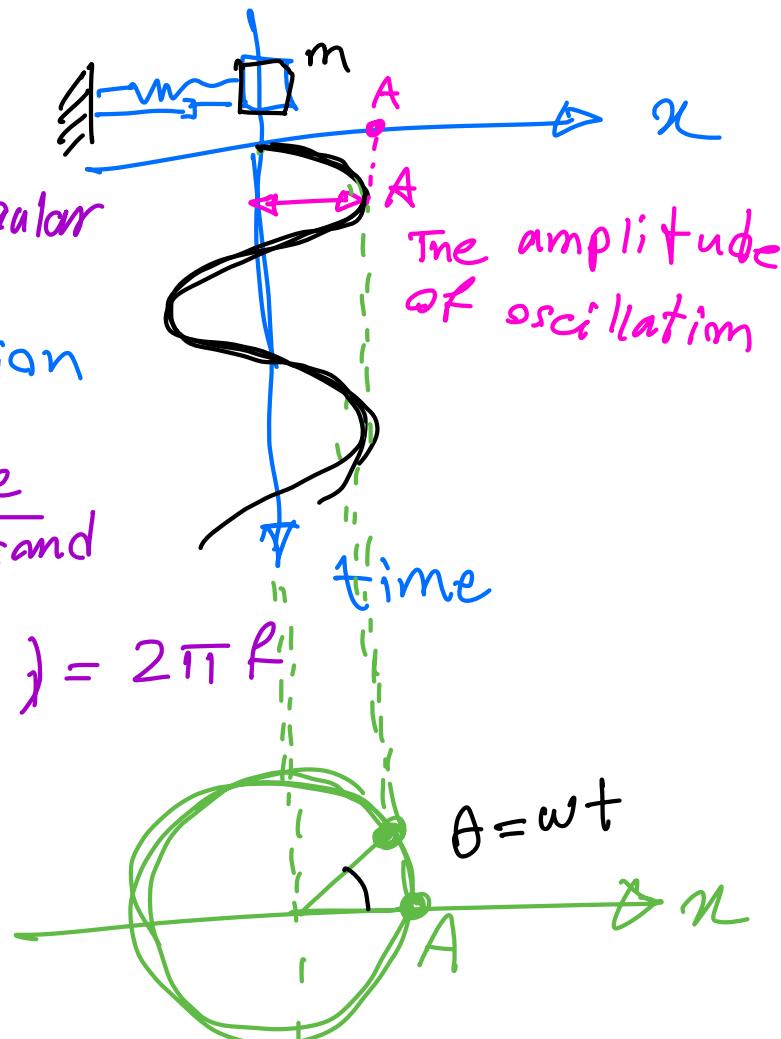
$\theta$ : Angular displacement

$\omega$  = angular velocity

$t$ : time

Displacement = Velocity  $\times$  time

$$\theta = \omega t$$



$$x = A e^{i\omega t} \rightarrow \dot{x} = A i \omega e^{i\omega t}$$

$$\rightarrow \ddot{x} = A (i\omega)^2 e^{i\omega t}$$

$$= -A \omega^2 e^{i\omega t}$$

$$F - c\dot{x} - Kx = m \ddot{x}$$

$$F - c(A i \omega e^{i\omega t}) - K A e^{i\omega t} = m (-A \omega^2 e^{i\omega t})$$

The response of the mass to the force is a function of the force

If the force is applied with the frequency of  $\omega$ . displacement  
 It is expected that the response is a function of the forced excitation with the same frequency.

$$F = F_0 e^{i\omega t} \quad \Rightarrow \quad x = A e^{i\omega t}$$

$F$  excitation  $x$

# Force excitation Frequency

$$F - c(A i w e^{i w t}) - K A e^{i w t} = m (-A w^2 e^{i w t})$$

$$F = F e^{i w t}$$

substitute and rearrang:

$$\cancel{m A w^2 e^{i w t}} - i c A w e^{i w t} - \cancel{K A e^{i w t}} = -F e^{i w t}$$

$$m A w^2 - i c w A - K A = -f$$

$$A = ?$$

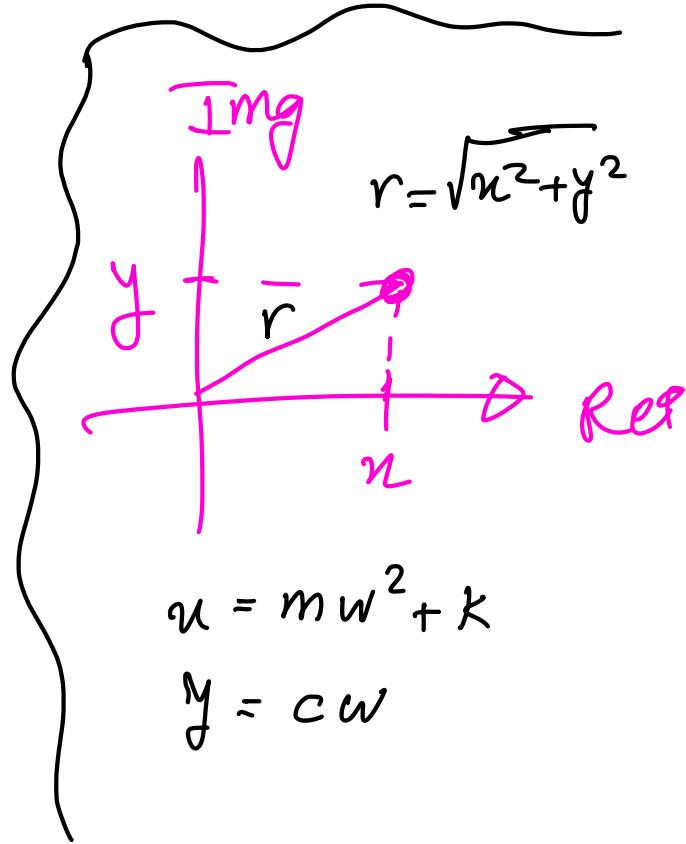
$$A = \frac{-F}{m w^2 - i c w - K}$$

$$A = \frac{-F}{(m w^2 - K) - i c w}$$

\overbrace{\phantom{0}}  
Real
\underbrace{\phantom{0}}  
Imag

$$A = \frac{-F}{(m\omega^2 - K) - i\omega} \frac{(m\omega^2 - K) + i\omega}{(m\omega^2 - K) + i\omega}$$

$$A = \frac{-F \left[ (m\omega^2 - K) - i\omega \right]}{(m\omega^2 - K)^2 - (\omega)^2}$$



$$|A| = \frac{F \sqrt{(m\omega^2 - K)^2 + (\omega)^2}}{(m\omega^2 - K)^2 + (\omega)^2}$$

Amplitude  
of the oscillation