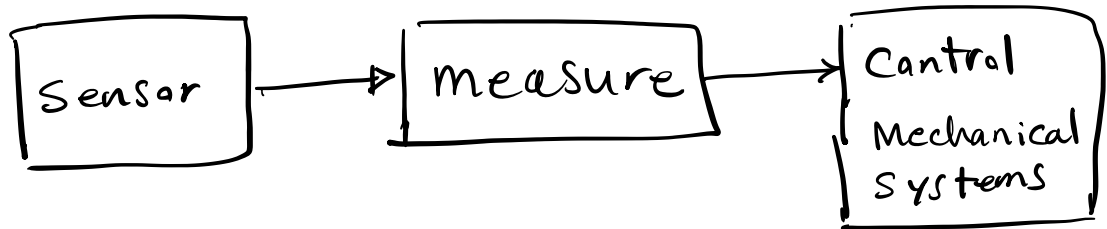
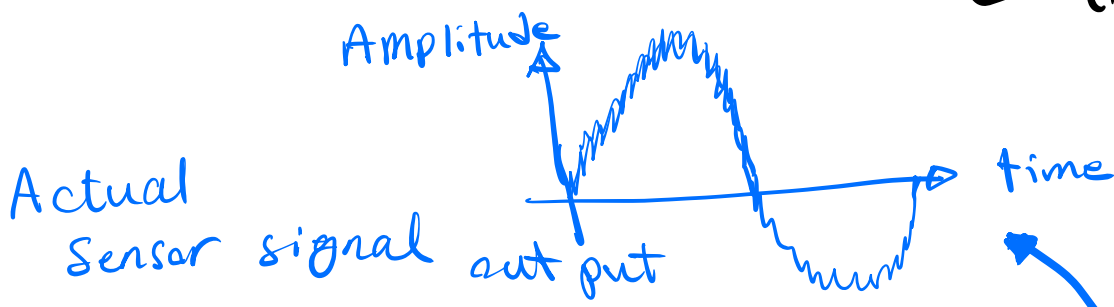
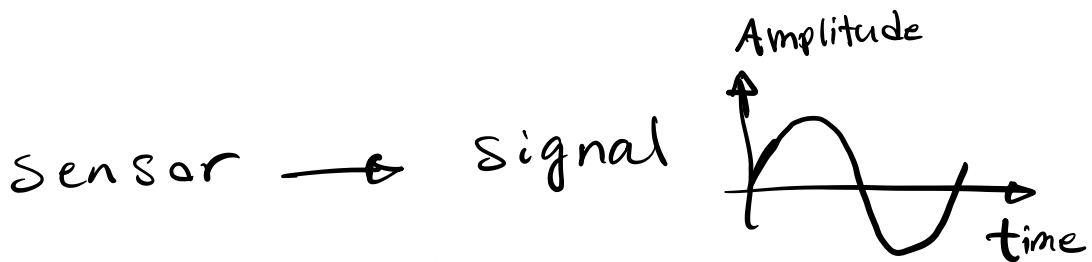


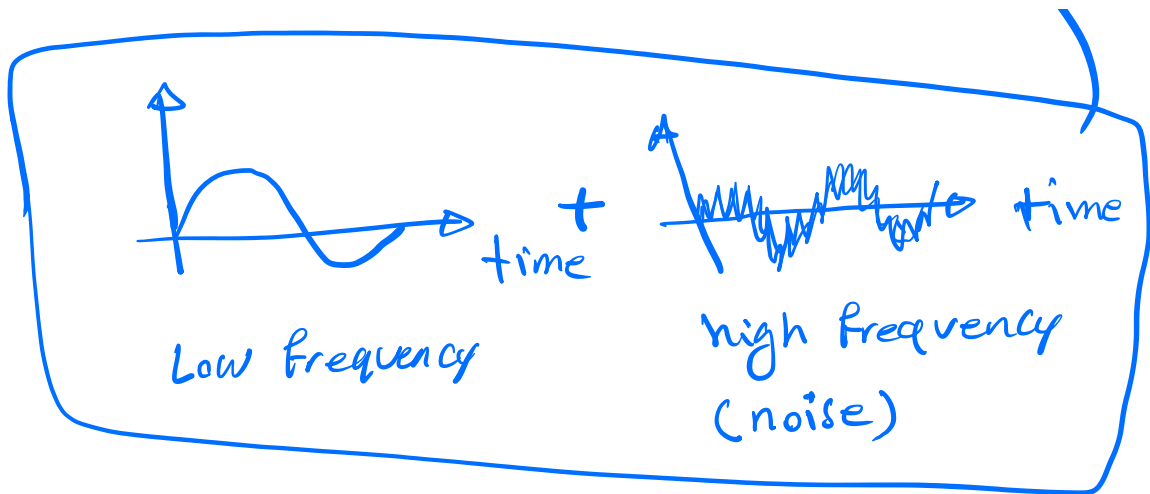
Filters and Amplifiers For Instrumentation in Mechanical systems (sensors)



Sensor output { includes noise
has very small amplitudes (milli volts)

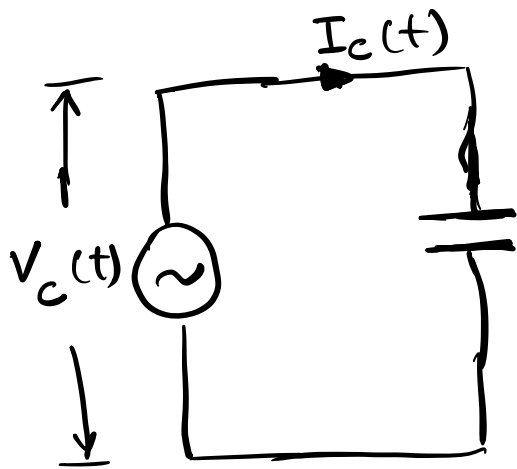
we need to remove noise from the sensor





- Capacitor circuits can be used as filters to remove noise from the sensor signal.
- Operational amplifiers are used to amplify the small magnitude signal from the sensor to larger magnitudes that can be measured.

Capacitors (Capacitive Reactance)



When a DC voltage is applied to a capacitor, the capacitor charges and no current flows in the circuit.

When AC voltage is applied the voltage is changing from a positive to a negative polarity at a rate determined by the frequency of the supply. The capacitor is charging and discharging.

Capacitive Reactance has the symbol X_c and has units

measured in Ohms the same as resistance (R). It is calculated using the following formula.

$$X_c = \frac{1}{2\pi f C} \quad \text{Capacitive Reactance formula}$$

Where

X_c : Capacitive Reactance in Ohms (Ω)

π (Pi) : 3.142

f : Frequency in Hertz (Hz)

C : Capacitance in Farads (F)

Example

calculate the capacitive reactance of a 220 nF capacitor at a frequency of 1 KHz, and at 20 KHz.

$$X_C = \frac{1}{2\pi fC}$$

At a frequency of 1 KHz:

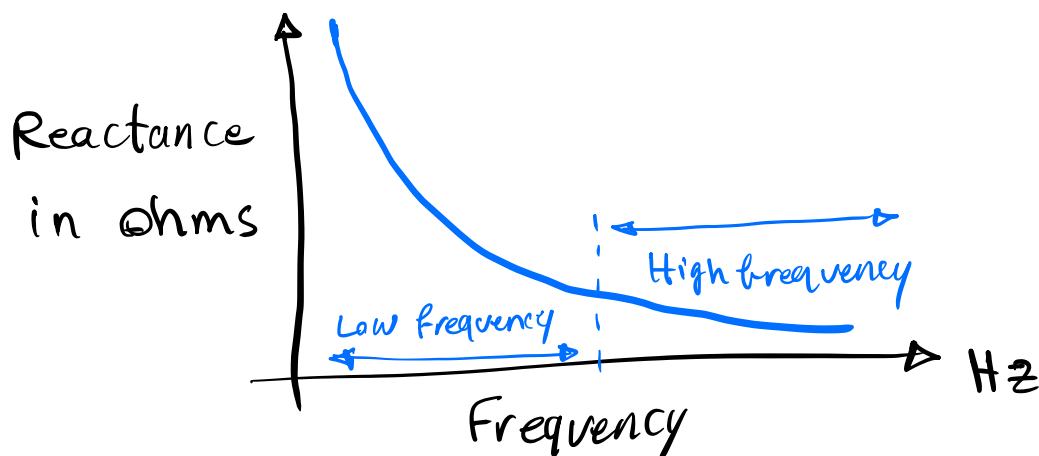
$$X_C = \frac{1}{2\pi fC} = \frac{1}{2\pi \times 1000 \times 220 \times 10^{-9}}$$

$$X_C = \underline{723.4 \Omega}$$

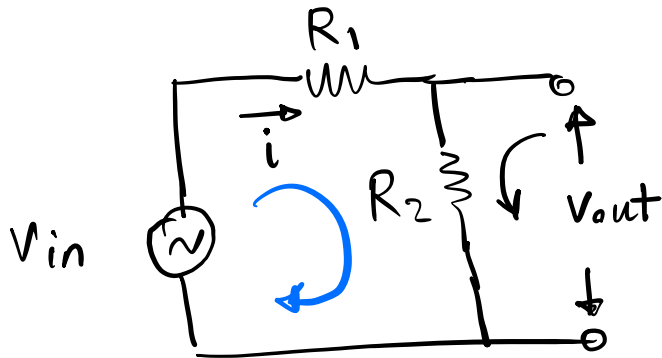
At a frequency of 20 KHz:

$$X_C = \frac{1}{2\pi fC} = \frac{1}{2\pi \times 20,000 \times 10^{-9}} = \underline{36.2 \Omega}$$

Capacitive Reactance vs. Frequency.



Voltage Divider circuit:



$$\begin{cases} V_{in} = R_1 i + R_2 i = (R_1 + R_2) i \\ V_{out} = R_2 i \Rightarrow i = \frac{V_{out}}{R_2} \end{cases}$$

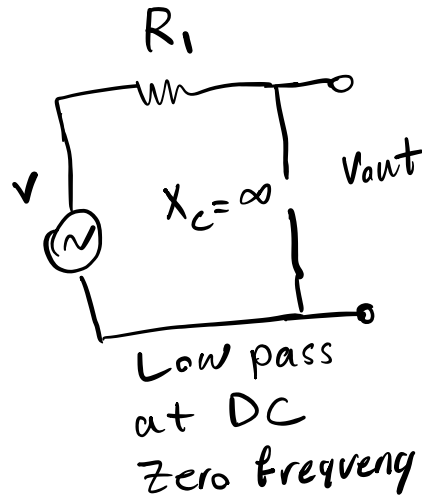
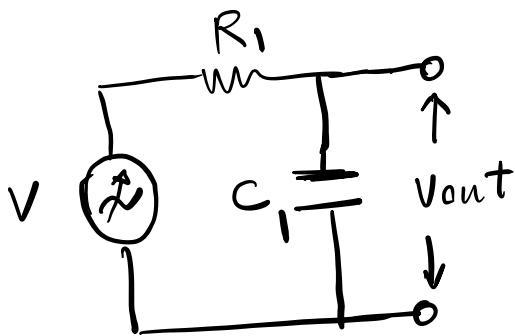
$$V_{in} = (R_1 + R_2) \frac{V_{out}}{R_2}$$

$$V_{out} = V_{in} \frac{R_2}{R_1 + R_2}$$

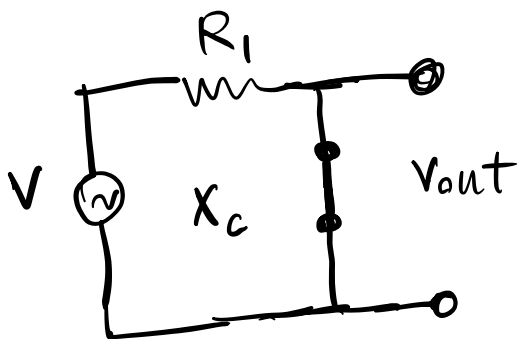
we have capacitive reactance X_c instead of resistors. which can be used instead of one of the resistors above in design of filters. This results

in a frequency-dependent RC voltage divider circuit. Low pass filters and high pass filters can be constructed by replacing one of the resistors in the voltage divider with a suitable capacitor as shown.

Low pass Filter



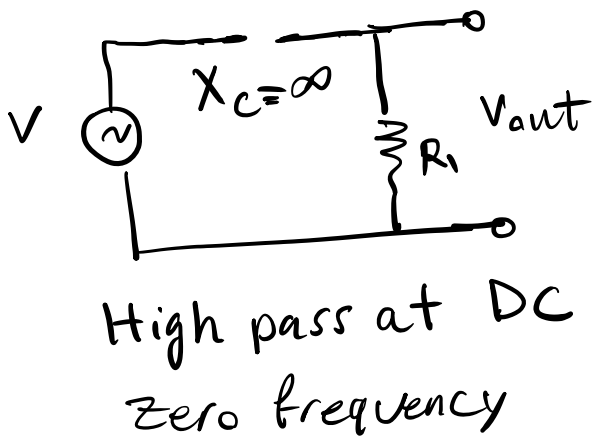
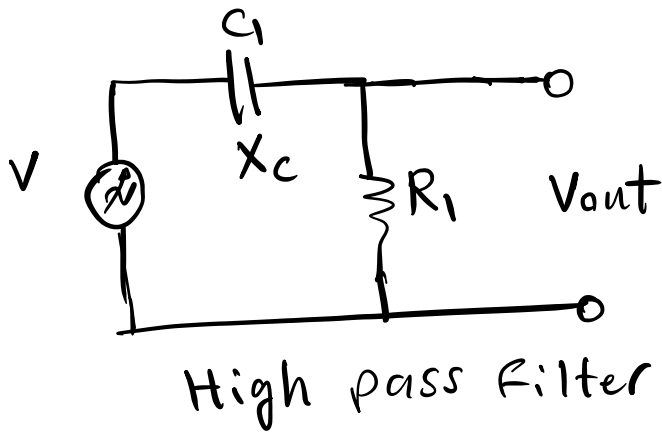
$$X_c = \frac{1}{2\pi fC} = \frac{1}{0} = \infty$$



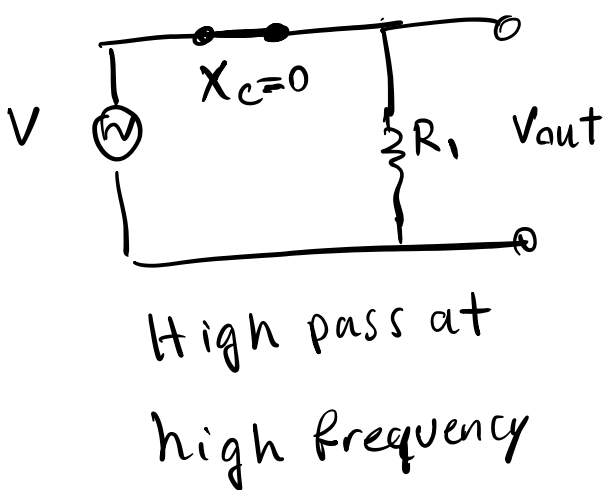
$$X_c = \frac{1}{2\pi fC} = \frac{1}{\infty} = 0$$

Low pass at high frequency

High pass Filter



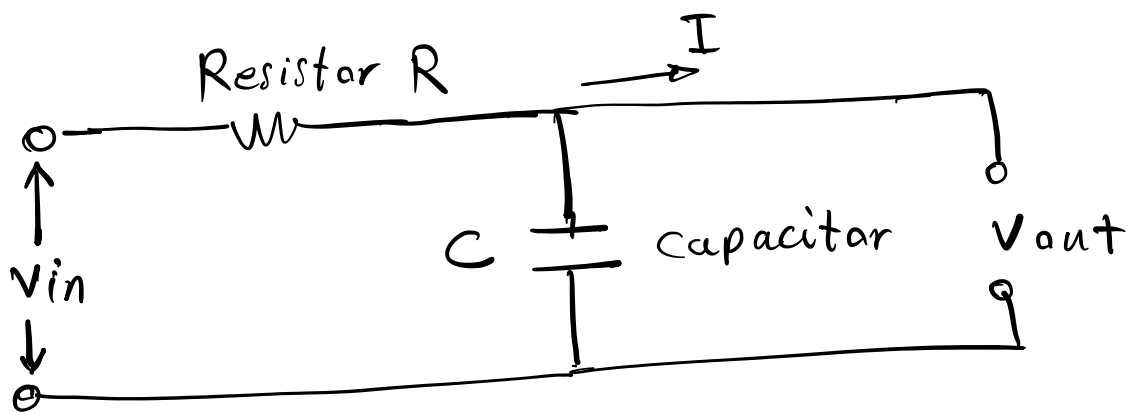
$$X_c = \frac{1}{2\pi f c} = \frac{1}{0} = \infty$$



$$X_c = \frac{1}{2\pi f c} = \frac{1}{\infty} = 0$$

The property of Capacitive Reactance, makes the capacitor ideal for use in AC filter circuits.

Passive Low pass Filter



A low pass Filter is a circuit that can be designed to modify or reject unwanted high frequencies of an electrical signal and accept or pass only low frequency signals.

passive filters are generally constructed using simple RC (Resistor-capacitor)

circuits, while higher frequency filters (above 100 kHz) are usually made from RLC (Resistor-Inductor-Capacitor) components.

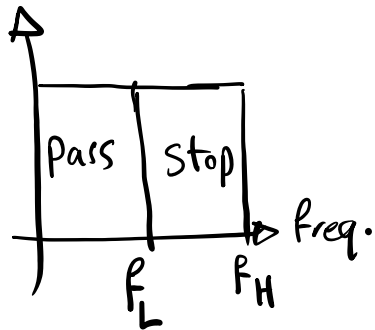
Passive filters are made up of a passive components such as resistors, capacitors and inductors, and have no amplifying elements (transistors, op-amp, etc) so have no signal gain, therefore their output level is always less than the input.

- The low pass Filter: only allows low frequency signal from 0 Hz to its cut-off frequency f_c point

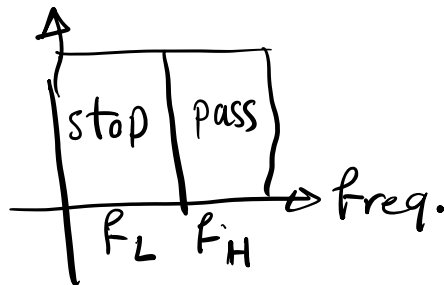
to pass while blocking any higher frequency

- The high pass Filter allows high frequency signals from its cut-off frequency, f_c point and higher to infinity to pass through while blocking those any lower.
- The band pass Filter allows signals falling within a certain frequency band setup between two points to pass through while blocking both the lower and higher frequencies of this frequency band.

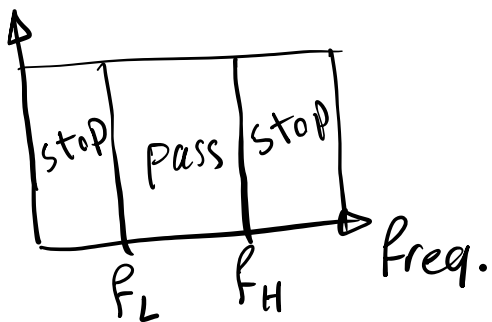
Ideal Filter response:



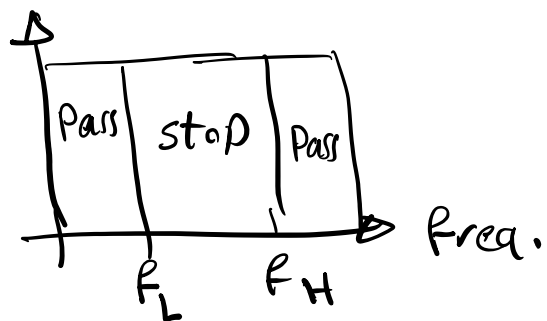
Low pass Filter



High pass Filter



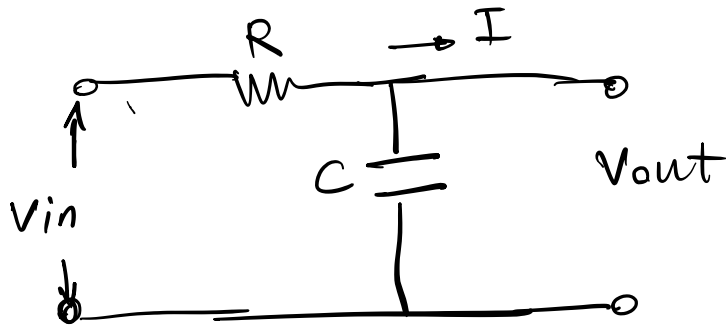
Band pass Filter




Band stop Filter

The frequency at which the transition occurs is called the "cut-off" or "corner" frequency.

RC Low pass Filter circuit



voltage divider circuit 

$$V_{out} = V_{in} \frac{R_2}{R_1 + R_2}$$

$R_1 + R_2$ is the total resistance.

in AC circuit the capacitive reactance

is $X_C = \frac{1}{2\pi f C}$ ohms

How do we add X_C to R ?

Opposition to current flow in an AC circuit is called impedance, symbol Z is used.

The impedance is calculated as:

$$Z = \sqrt{R^2 + X_C^2}$$

RC Divider Equation:

$$V_{out} = V_{in} \frac{X_C}{\sqrt{R^2 + X_C^2}} = V_{in} \frac{X_C}{Z}$$

So, by using the divider equation of two resistors in series and substituting for impedance we can calculate the output voltage of an RC Filter for any given frequency.

Example

A Low pass Filter circuit consisting of a resistor of 4.7 k Ω in series with capacitor of 47 nF is connected across a 10 v sinusoidal supply. Calculate the output voltage (V_{out}) at a frequency of 100 Hz, and 10 kHz.

voltage output at 100 Hz:

$$X_C = \frac{1}{2\pi fC} = \frac{1}{2\pi \times 100 \times 47 \times 10^{-9}} = 33\,863\,\Omega$$

$$V_{out} = V_{in} \times \frac{X_C}{\sqrt{R^2 + X_C^2}} = 10 \times \frac{33\,863}{\sqrt{4700^2 + 33863^2}}$$

$$V_{out} = 9.9\,v$$

Voltage output at a frequency of

10,000 Hz (10 kHz):

$$X_c = \frac{1}{2\pi fC} = \frac{1}{2\pi \times 10000 \times 47 \times 10^{-9}} = 338.6 \Omega$$

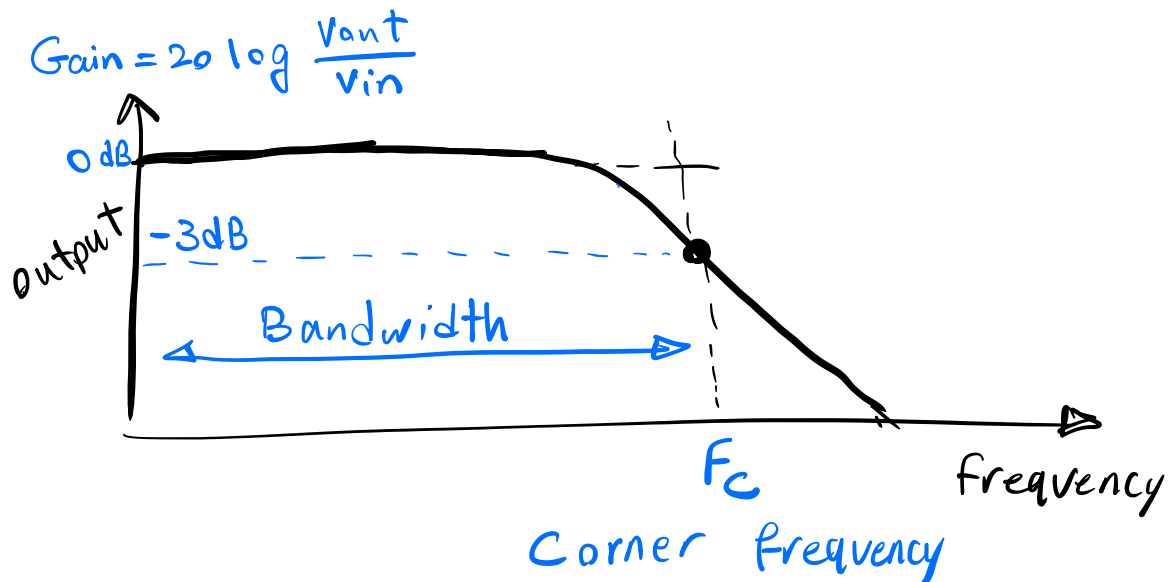
$$V_{out} = V_{In} \frac{X_c}{\sqrt{R^2 + X_c^2}} = 10 \times \frac{338.6}{\sqrt{4700^2 + 338.6^2}}$$

$$= 0.718 \text{ V}$$

From the results, we can see that as frequency applied to the RC network increases from 100 Hz to 10 kHz, the voltage dropped across the capacitor and therefore the output voltage (V_{out}) from the circuit decreases from 9.9 V to 0.718 V.

Frequency response of a 1st-order

Low pass Filter :



The frequency response of the filter is nearly flat for low frequencies and all of the input signal is passed directly to the output, resulting in a gain of nearly 1 ($\frac{V_{out}}{V_{in}} = 1$ $\Rightarrow V_{out} = V_{in}$), called unity, until it reaches its cut-off frequency

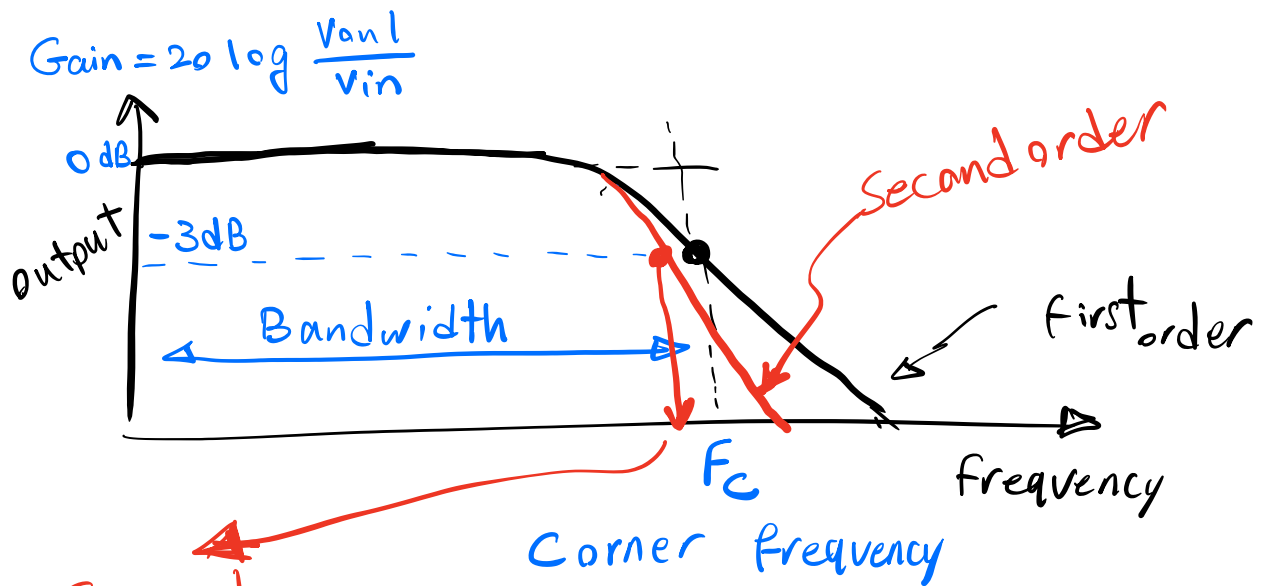
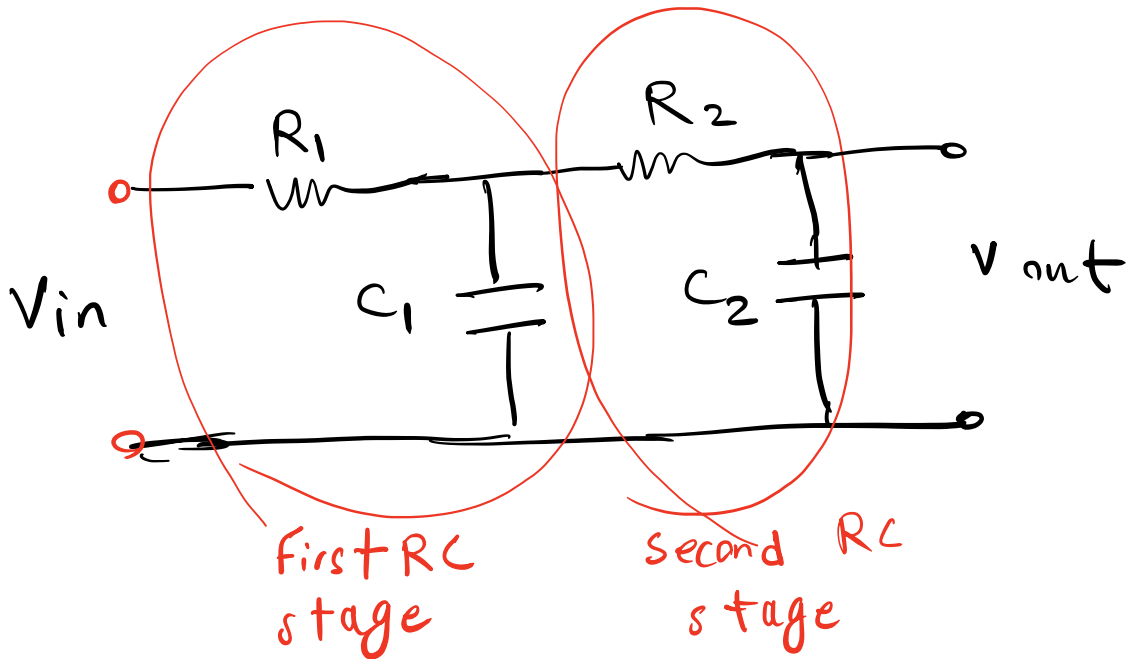
point (f_c). This is because the reactance of the capacitor is high at low frequencies and blocks any current flow through the capacitor.

cut-off frequency:

$$f_c = \frac{1}{2\pi RC} \Rightarrow C = \frac{1}{2\pi f_c R}$$

Design
the low pass filter by
calculating a suitable capacitance
 C for the desired frequency
cut-off f_c and an available
resistor (for example $10\text{ k}\Omega$)

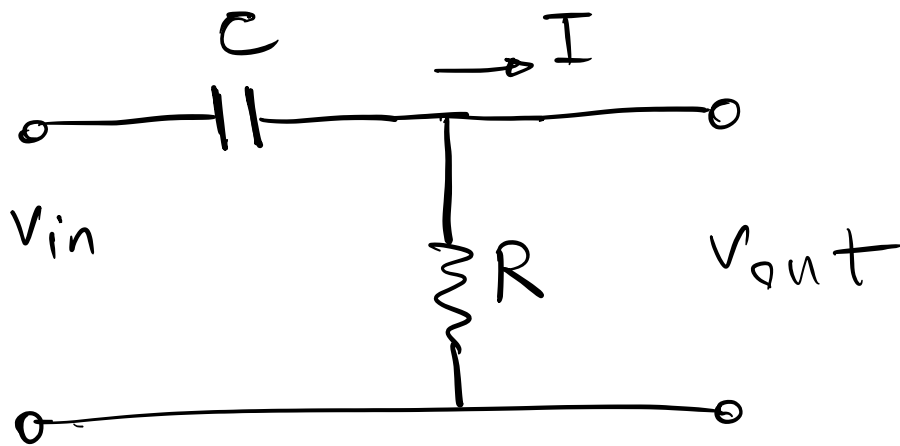
Second-order Low pass Filter



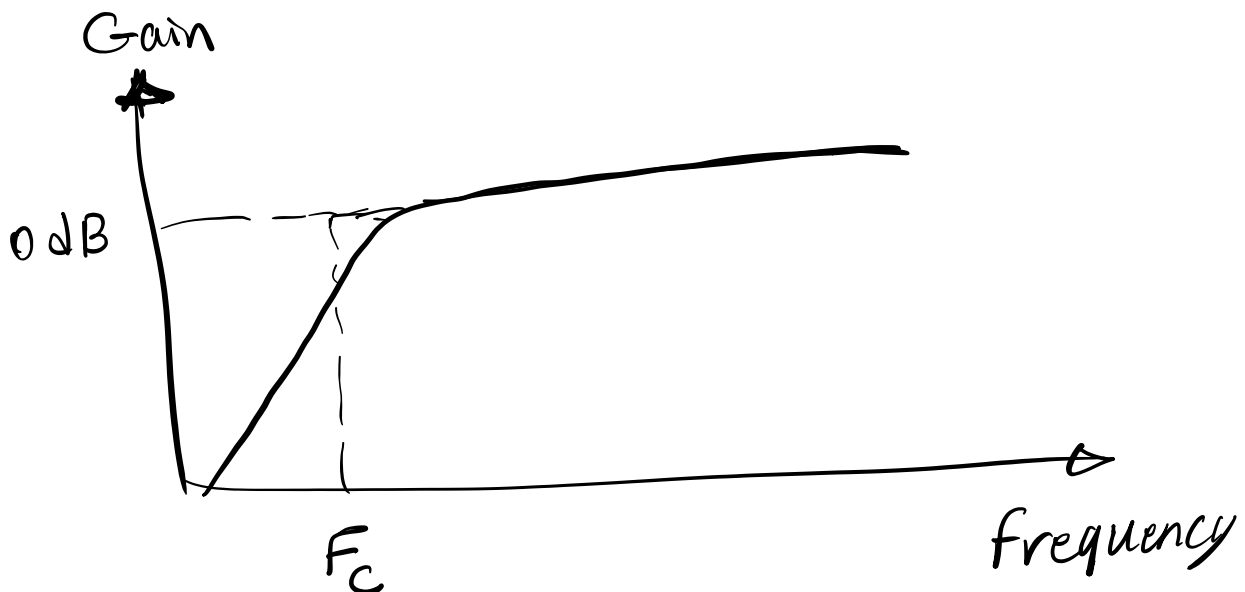
Second order corner frequency

$$F_c = \frac{1}{2\pi \sqrt{R_1 C_1 R_2 C_2}} \text{ Hz}$$

Passive High pass Filter



Frequency response of a 1st order High pass filter



cut-off frequency:

$$f_c = \frac{1}{2\pi RC}$$

$$\frac{V_{out}}{V_{in}} = A_v = \frac{R}{\sqrt{R^2 + X_c^2}} = \frac{R}{Z}$$

at low freq.: $X_c \rightarrow \infty$, $V_{out} = 0$

at high freq.: $X_c \rightarrow 0$, $V_{out} = V_{in}$

Example

calculate the cut-off or

"breakpoint" frequency (f_c) for

a passive high pass filter

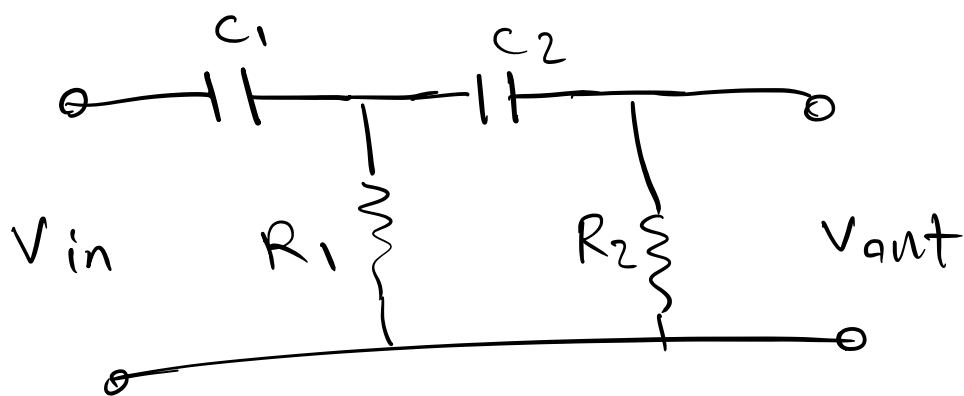
considering 82 pF capacitor

in series with $240\text{ k}\Omega$ resistor

$$f_c = \frac{1}{2\pi RC} = \frac{1}{2\pi \times 240000 \times 82 \times 10^{-12}}$$

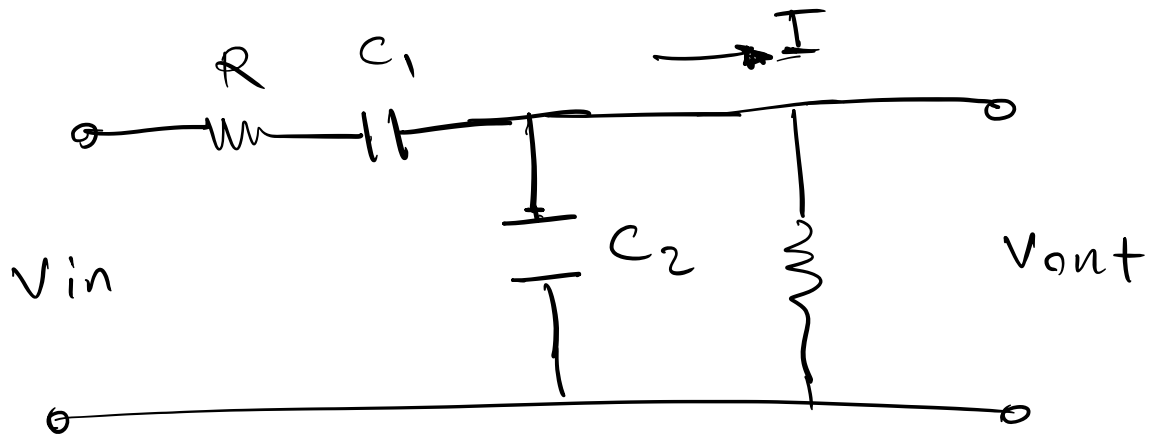
$$f_c = 8087\text{ Hz or } 8\text{ kHz}$$

second-order High Pass Filter



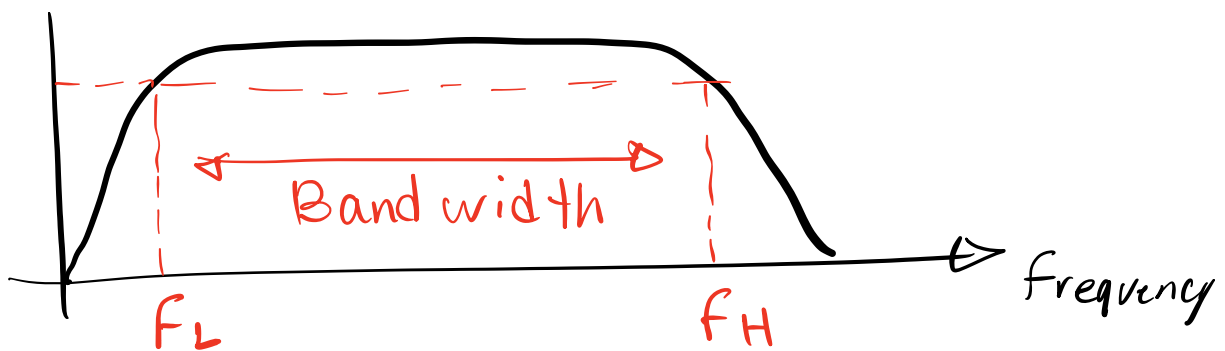
$$f_c = \frac{1}{2\pi \sqrt{R_1 C_1 R_2 C_2}} \text{ Hz}$$

Passive Band pass Filter



Passive Band pass Filters can be made by connecting together a low pass filter with a high pass filter.

Frequency response



The upper and lower cut-off frequency points for a band pass filter can be found using the same formula as that for both the low and high pass filters:

$$f_c = \frac{1}{2\pi RC} \text{ Hz}$$

Example

A second-order band pass filter is to be constructed using RC components that will only allow a range of frequencies to pass above 1 kHz and below 30 kHz

use both resistors to be $10\text{ k}\Omega$.
Calculate the two capacitor values.

The high Pass stage:

cut-off frequency is $f_L = 1\text{ kHz}$

$$C_1 = \frac{1}{2\pi f_L R} = \frac{1}{2\pi \times 1000 \times 10,000} = 15.9\text{ nF}$$

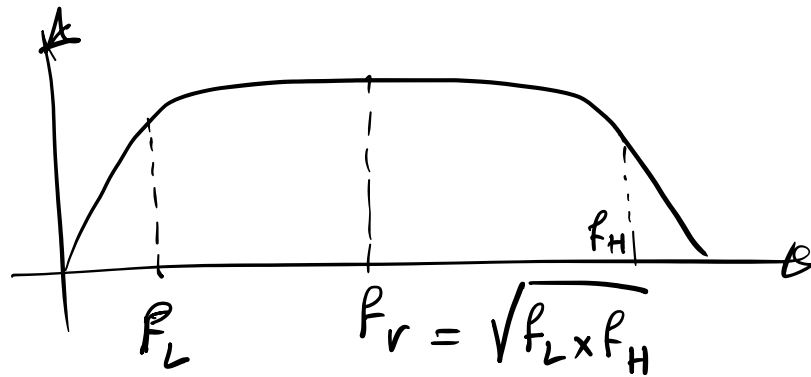
The nearest preferred value $C_1 = 15\text{ nF}$

The Low Pass Filter stage

$$f_H = 30\text{ kHz}$$

$$C_2 = \frac{1}{2\pi f_H R} = \frac{1}{2\pi \times 30000 \times 10000} = 530\text{ pF}$$

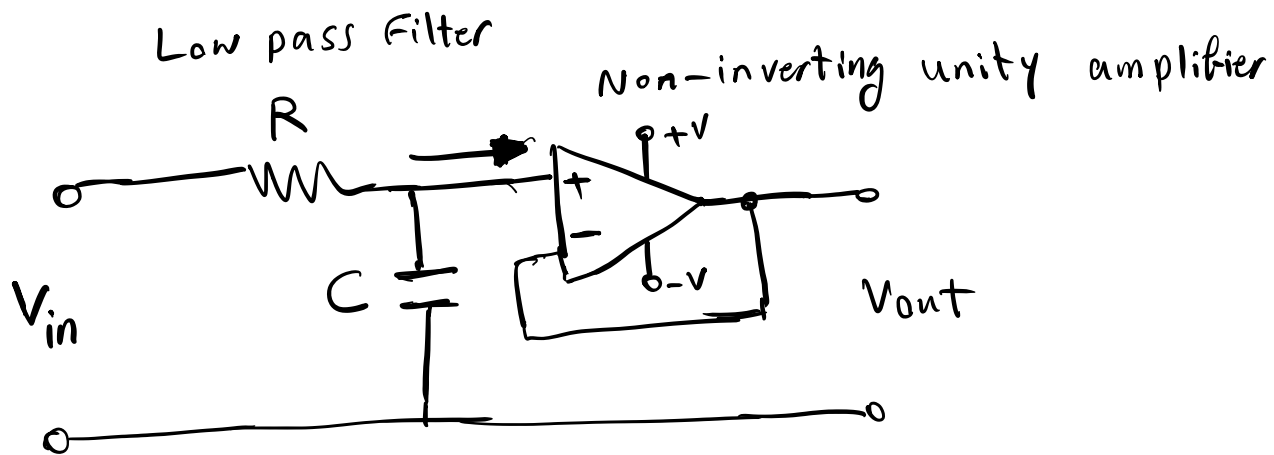
Center Frequency



Buffering individual Filter stages

one way of combining amplification and filtering into the same circuit would be to use an operational Amplifier (op-amp). The op-amp not only introduce gain but provide isolation between stages, which known as Active Filters.

Active Low Pass Filter

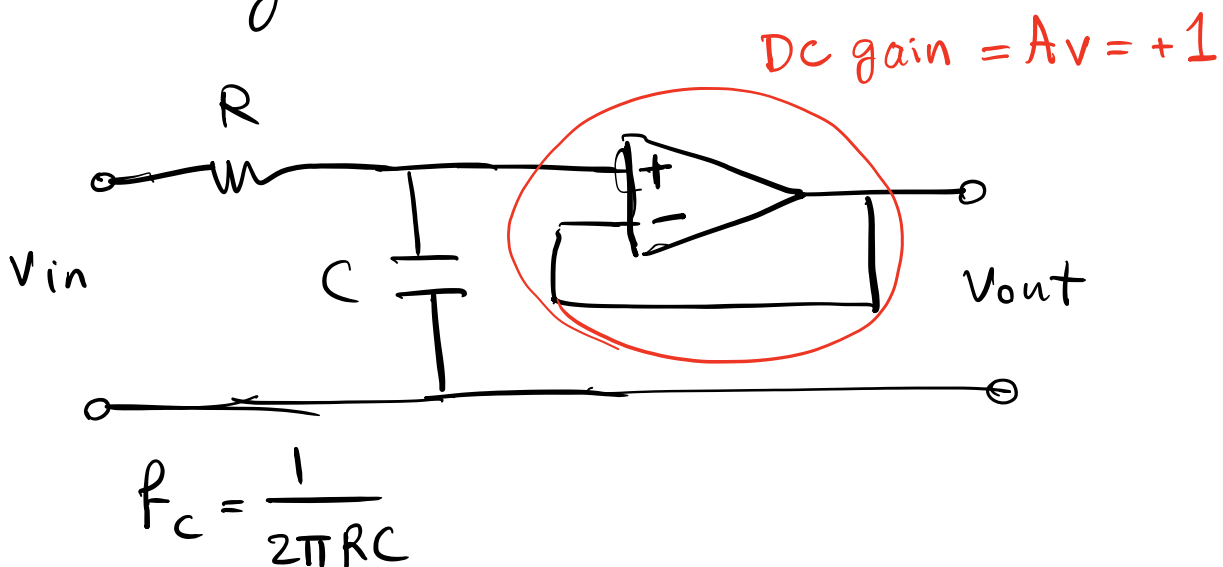


By combining a basic RC Low Pass Filter circuit with an operational amplifier we can create an Active Low pass Filter circuit complete with amplification.

The main disadvantage of passive filters is that the amplitude of the output signal is less than the input (the gain is never greater than 1

be cause the load impedance affects the filters output)

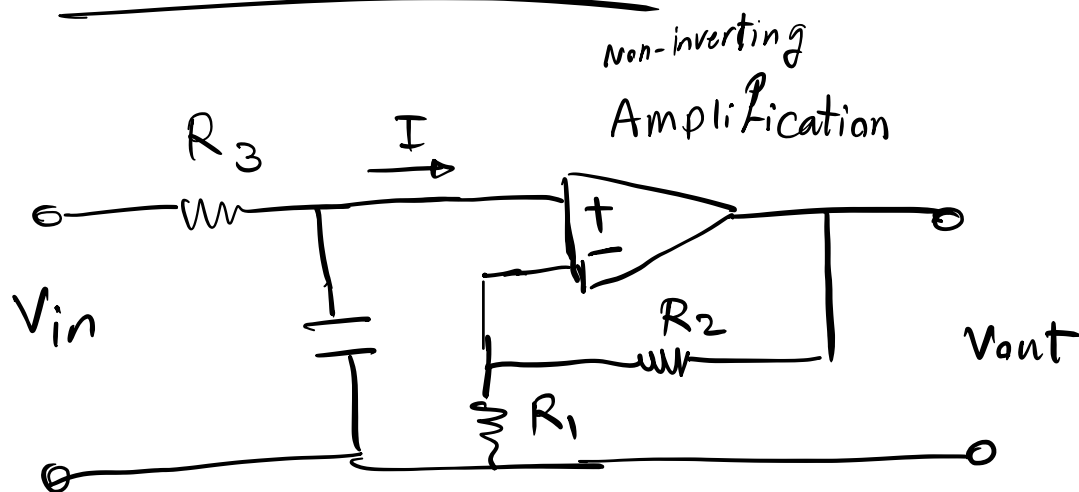
with passive filter circuits containing multiple stage, this loss in signal called "Attenuation" and can become severe. one way of restoring or controlling this loss of signal is by using amplification by using Active Filters.



The advantage of this configuration

is that the op-amp prevents excessive loading on the filter's output, while preventing the filter's cut-off frequency point from being affected.

Active Low Pass Filter with Amplification



Amplification factor = DC gain

$$= \left[1 + \frac{R_2}{R_1} \right]$$

For a non-inverting amplifier circuit the magnitude of the voltage gain for the filter is given as a function of the feedback resistor (R_2) and input resistor (R_1):

$$\text{DC gain} = \left[1 + \frac{R_2}{R_1} \right] \rightarrow A_F$$

Gain of a first-order low pass filter

$$\text{Voltage Gain } (A_V) = \frac{V_{\text{out}}}{V_{\text{in}}} = \frac{A_F}{\sqrt{1 + \left(\frac{f}{f_c}\right)^2}}$$

where

A_F = the pass band of the filter $\left(1 + \frac{R_2}{R_1}\right)$

f = the frequency of the input

signal in Hertz (Hz)

f_c = the cut-off frequency in Hertz

Example

Design a non-inverting active low pass

filter circuit that has a gain of

ten at low frequencies, high frequency

cut-off or corner frequency of 159 Hz

and an input impedance of 10 k Ω .

The voltage gain of a non-inverting

operational amplifier is given as:

$$A_F = 1 + \frac{R_2}{R_1} = 10$$

Assume a value for resistor

R_1 of 1 k Ω rearranging the

Formula above gives a value of R_2 of :

$$1 + \frac{R_2}{R_1} = 10$$

$$\frac{R_2}{R_1} = 10 - 1$$

$$R_2 = (10 - 1) R_1$$

$$R_2 = (10 - 1) 1 \text{ k}\Omega = 9 \text{ k}\Omega$$

However, a $9 \text{ k}\Omega$ resistor does not exist so the next preferred value of $9.1 \text{ k}\Omega$ is used instead. Converting this voltage gain to

an equivalent decibel dB

Value give:

$$\begin{aligned}\text{Gain in dB} &= 20 \log A \\ &= 20 \log 10 = 20 \text{ dB}\end{aligned}$$

$$f_c = 159 \text{ Hz} \quad \text{Low pass filter}$$

$$f_c = \frac{1}{2\pi RC}$$

$$C = \frac{1}{2\pi f_c R} = \frac{1}{2\pi \times 159 \times 10000} = 100 \text{ nF}$$

$$C = 100 \text{ nF}$$

