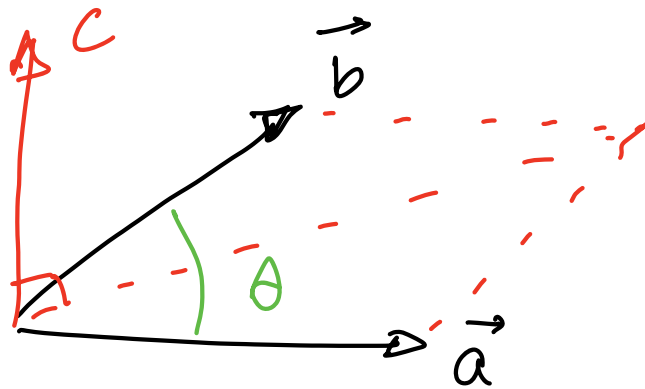


# Cross product

The cross product of  $\vec{a}$  and  $\vec{b}$  is given by:

$$\vec{a} \times \vec{b} = \vec{c}$$

$\vec{c}$  is the cross product of  $\vec{a}$  and  $\vec{b}$



$$\vec{a} \times \vec{b} = |\vec{a}| |\vec{b}| \sin \theta$$

$\theta$  is the angle between  $\vec{a}$  and  $\vec{b}$

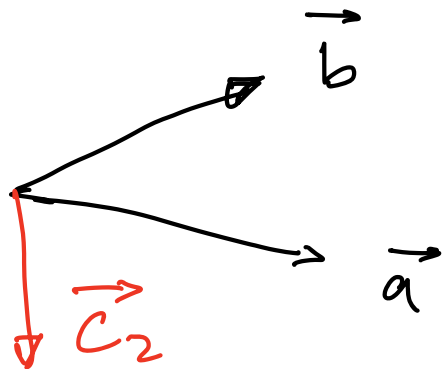
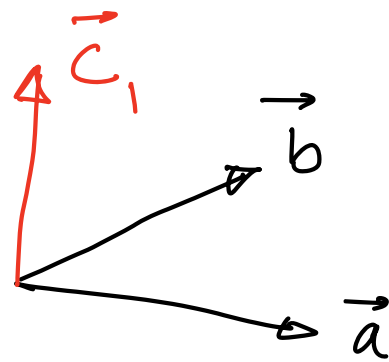
The direction of  $\vec{c}$  is given by the

right hand rule.

$$\vec{a} \times \vec{b} = \vec{c}_1$$

$$\vec{b} \times \vec{a} = \vec{c}_2$$

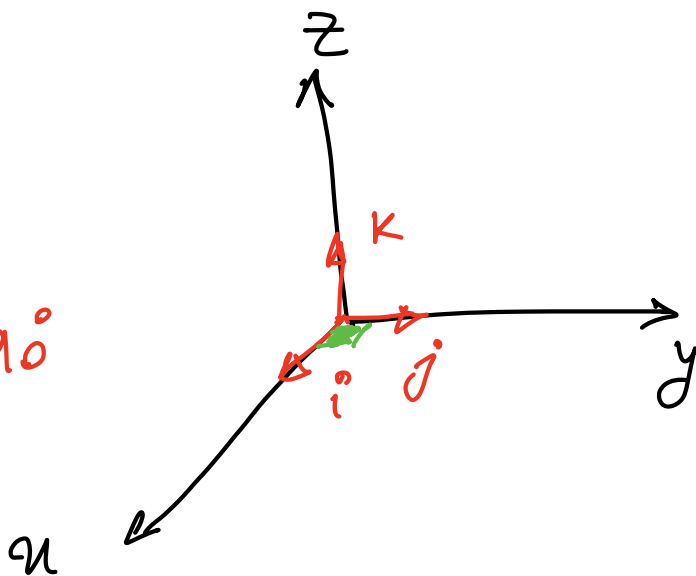
$$\vec{c}_1 = -\vec{c}_2$$



Therefore, the order of the cross product is important.

$$\hat{i} \times \hat{j} = \hat{k}$$

$$\begin{aligned} \hat{i} \times \hat{j} &= |\hat{i}| |\hat{j}| \sin 90^\circ \\ &= 1 \cdot 1 \cdot 1 \end{aligned}$$



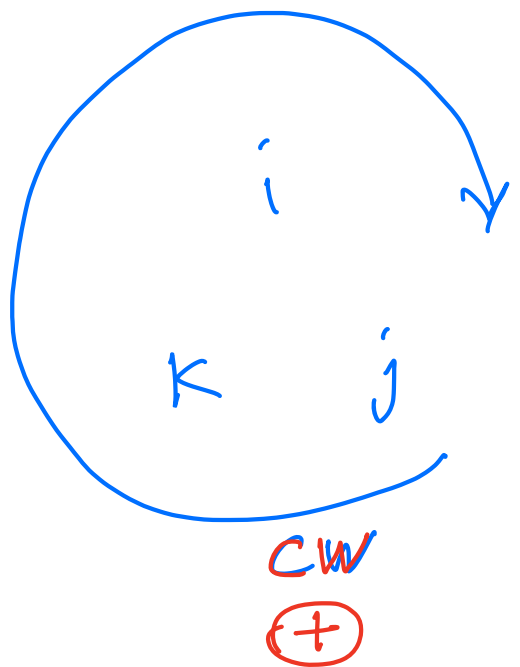
$$\begin{aligned} \hat{i} \times \hat{i} &= |\hat{i}| |\hat{i}| \sin(0) \\ &= 1 \cdot 1 \cdot 0 = 0 \end{aligned}$$

$$\hat{j} \times \hat{k} = \hat{i}$$

$$\hat{k} \times \hat{i} = \hat{j}$$

$$\hat{j} \times \hat{i} = -\hat{k}$$

$$\hat{k} \times \hat{j} = -\hat{i}$$

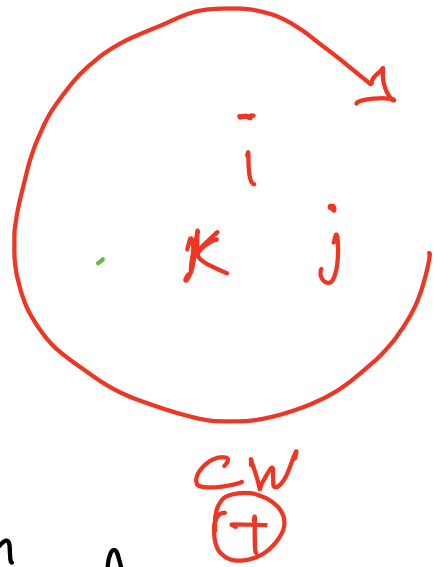


## Example

$$\vec{a} = 2\hat{i} - 3\hat{k}$$

$$\vec{b} = 3\hat{i} - \hat{j} + \hat{k}$$

$$\vec{a} \times \vec{b} = ?$$



$$\vec{a} \times \vec{b} = (2\hat{i} - 3\hat{k}) \times (3\hat{i} - \hat{j} + \hat{k})$$

$$= 6 \underline{\hat{i} \times \hat{i}} - 2 \hat{i} \times \hat{j} + 2 \hat{i} \times \hat{k}$$

$$- 9 \underbrace{\hat{k} \times \hat{i}}_{\hat{j}} + 3 \underbrace{\hat{k} \times \hat{j}}_{-\hat{i}} - \underline{3 \hat{k} \times \hat{k}}_0$$

$$= -2\hat{k} - 2\hat{j} - 9\hat{j} - 3\hat{i}$$

$$= -3\hat{i} - 11\hat{j} - 2\hat{k}$$

← Now use the determinant method:

$$\vec{a} = 2\hat{i} - 3\hat{k}$$

$$\vec{b} = 3\hat{i} - \hat{j} + \hat{k}$$

$$\vec{a} \times \vec{b} = ?$$

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & 0 & -3 \\ 3 & -1 & 1 \end{vmatrix}$$

$$= \hat{i} [(0)(1) - (-3)(-1)]$$

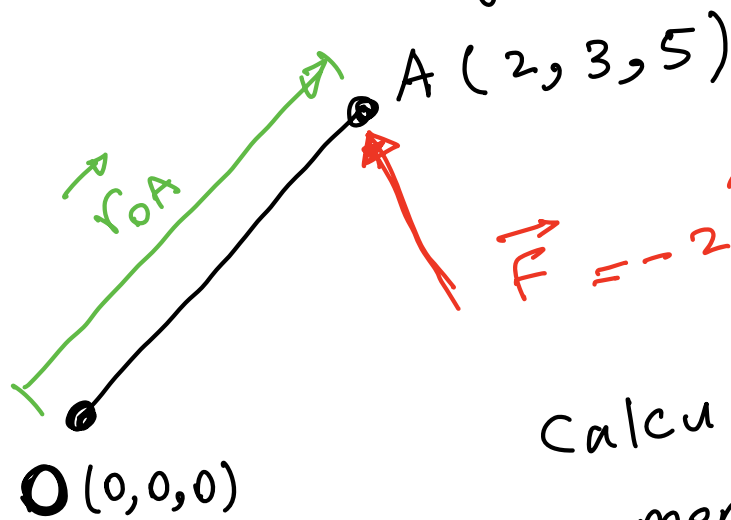
$$- \hat{j} [(2)(1) - (-3)(3)]$$

$$+ \hat{k} [(2)(-1) - (0)(3)]$$

$$= -3\hat{i} - 11\hat{j} - 2\hat{k}$$

Example of an application:

Calculating moments:



$$\vec{F} = -2\hat{i} + 0\hat{j} + 4\hat{k}$$

Calculate the moment of force  $\vec{F}$  applied to the rod OA about point O.

$$\vec{M}_O = \vec{r}_{OA} \times \vec{F}$$

$$\vec{M}_O = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & 3 & 5 \\ -2 & 0 & 4 \end{vmatrix} = \hat{i}(12) - \hat{j}(8 - (-10)) + \hat{k}(-(-3)(-2))$$
$$= 12\hat{i} - 18\hat{j} + 6\hat{k}$$

## Example

The force of  $F = 30\text{N}$  acts on the bracket.

$$\alpha = 60^\circ \quad \beta = 60^\circ \quad \gamma = 45^\circ$$

Find the moment of  $\vec{F}$  about the  $a-a$  axis.

- Find  $\vec{u}_a$  :  $\vec{u}_a = \hat{j}$

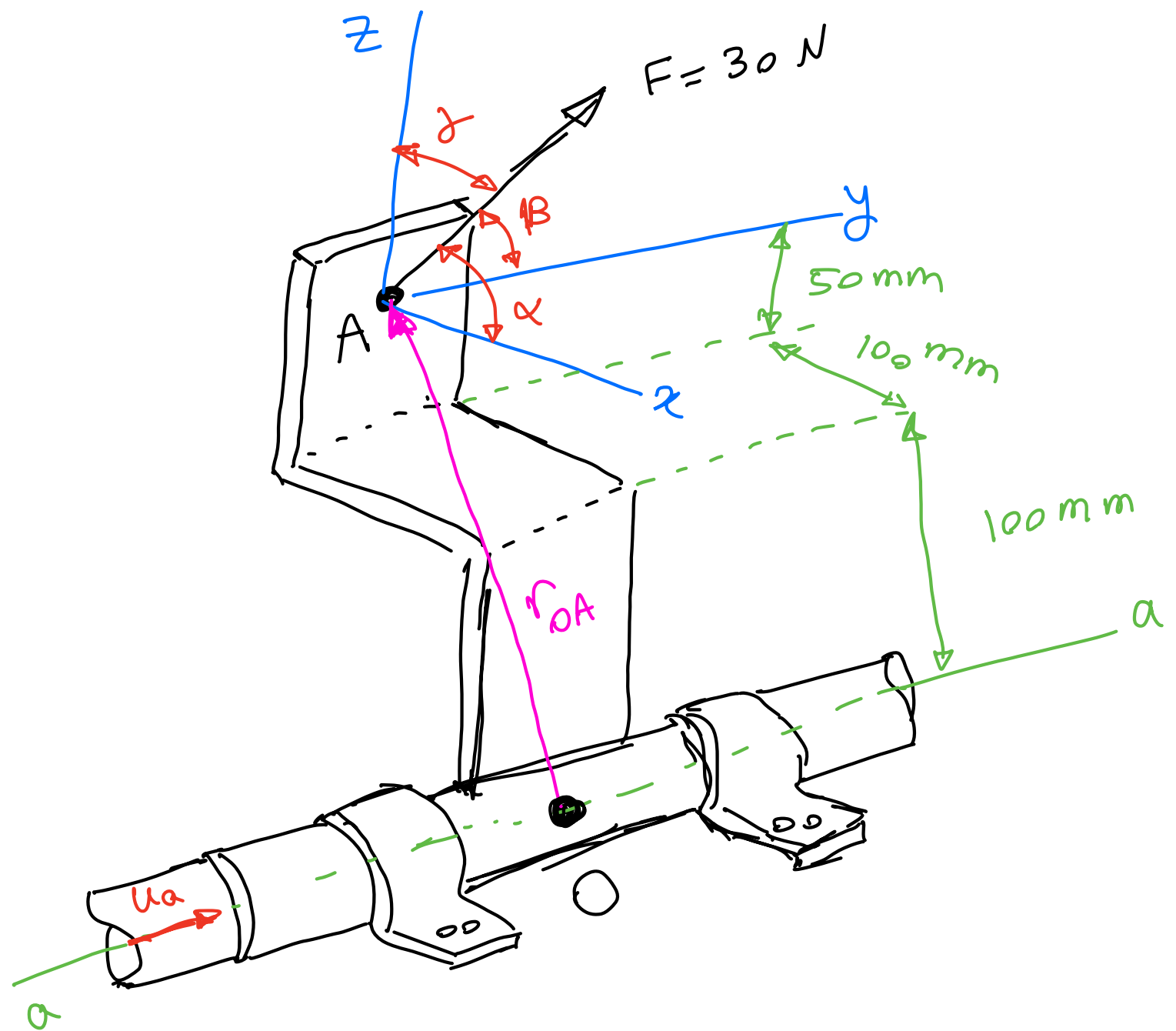
- Find  $\vec{r}_{OA}$  :

$$\vec{r}_{OA} = (x_A - x_0)\hat{i} + (y_A - y_0)\hat{j} + (z_A - z_0)\hat{k}$$

$$= (0 - 100)\hat{i} + (0 - 0)\hat{j} + (0 - (-150))\hat{k}$$

$$= -100\hat{i} + 0\hat{j} + 150\hat{k}$$

or in meters:  $\vec{r}_{OA} = -0.1\hat{i} + 0.15\hat{k}$



— Find  $\vec{F}$ :

$$\vec{F} = 30 \text{ N} (\cos 60^\circ \hat{i} + \cos 60^\circ \hat{j} + \cos 45^\circ \hat{k})$$

$$\vec{F} = (15 \hat{i} + 15 \hat{j} + 21.21 \hat{k}) \text{ N}$$

- Find  $\vec{M}_O$ :

$$\vec{M}_O = \vec{r}_{OA} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -0.1 & 0 & 0.15 \\ 15 & 15 & 21.21 \end{vmatrix}$$

$$\begin{aligned} \vec{M}_O &= \hat{i} \left[ (0)(21.21) - (0.15)(15) \right] \\ &\quad - \hat{j} \left[ (-0.1)(21.21) - (0.15)(15) \right] \\ &\quad + \hat{k} \left[ (-0.1)(15) - (0)(15) \right] \\ &= -2.25 \hat{i} + 4.37 \hat{j} - 1.5 \hat{k} \end{aligned}$$

$$\begin{aligned} \vec{u}_a \cdot \vec{M}_a &= (\hat{j}) \cdot (-2.25 \hat{i} + 4.37 \hat{j} - 1.5 \hat{k}) \\ &= 4.37 \end{aligned}$$

The magnitude of  
the component of  
the moment along a-a  
axis



To find this component in a vector form, you can multiply the magnitude by the direction of a-axis, as below:

$$\vec{M}_{a\text{-axis}} = 4.37 \vec{u}_a = 4.37 \hat{j}$$

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